

Can magnetic-field windup kill the r-mode instability of neutron stars?

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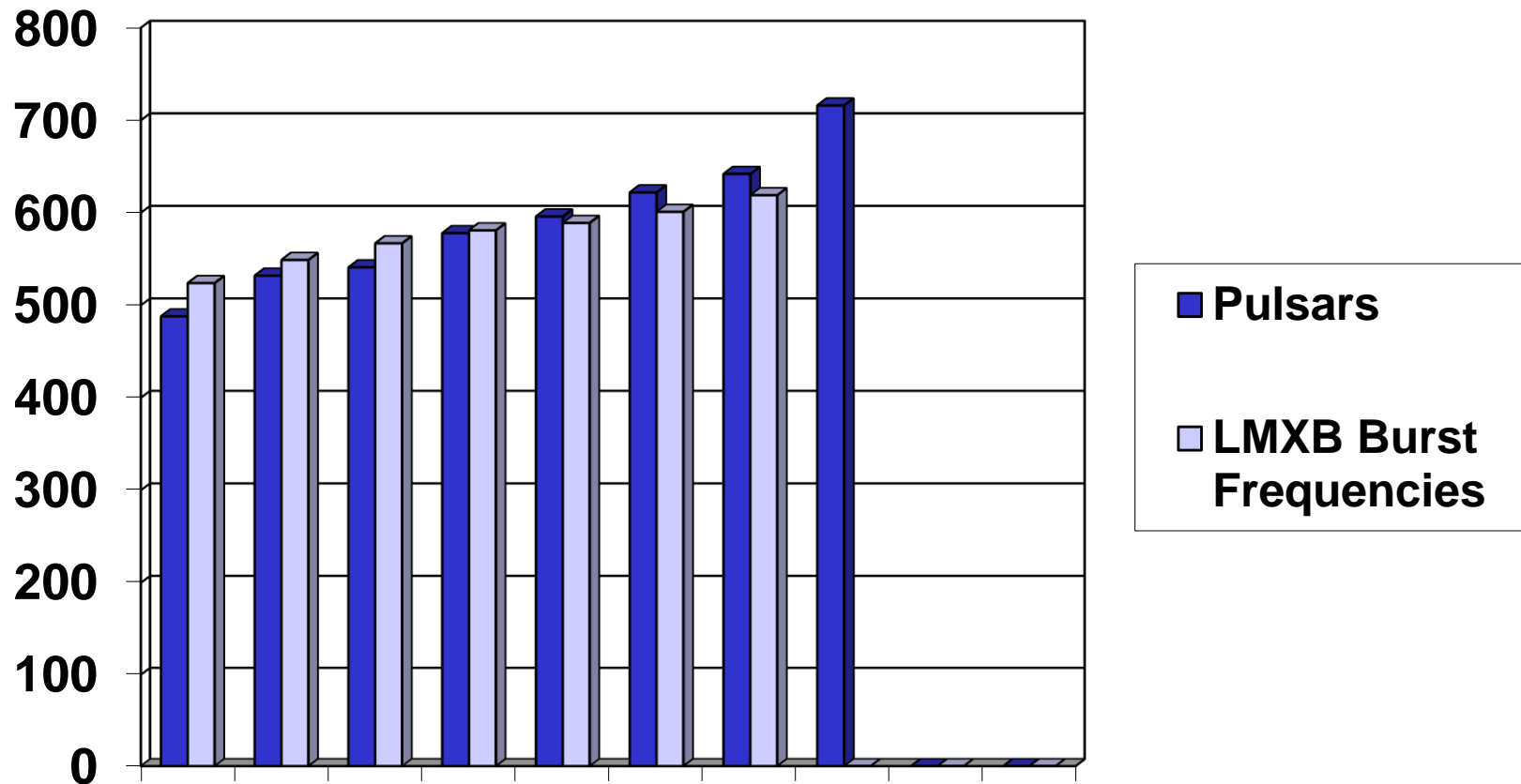
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All or nearly all of the fastest spinning neutron stars we observe are not young stars but are instead old neutron stars that have been spun up by accretion from a companion.



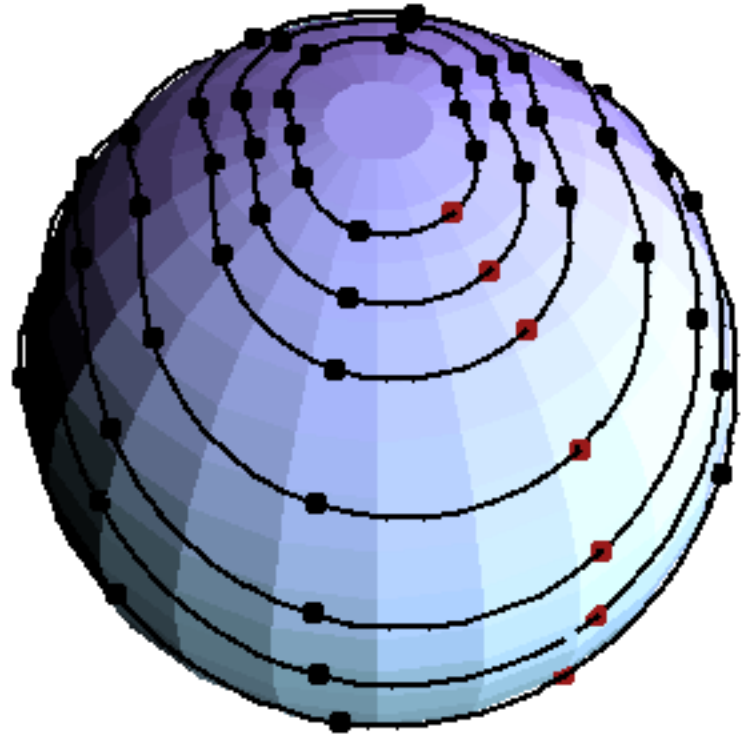
The angular velocities of observed neutron stars show a cutoff below 800 Hz.



This limit on spin may be set by a gravitational-wave driven (CFS) instability of an r -mode – a perturbation of the fluid velocity

$$\delta \mathbf{v} \propto \mathbf{r} \times \nabla Y_{22} e^{\beta t}$$

For old accreting stars, the growth time β^{-1} is months or years.

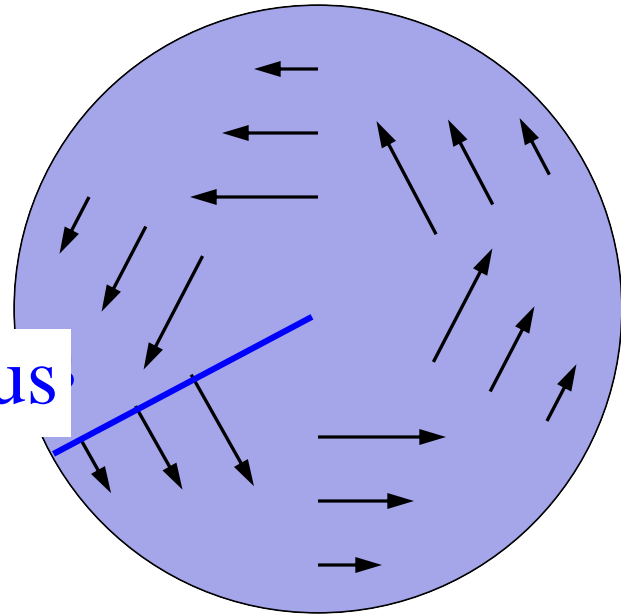


Animation by Chad Hanna

At second-order in perturbation theory,
radiation-reaction and quadratic terms in the
perturbed Euler equation drive an
exponentially growing differential rotation.

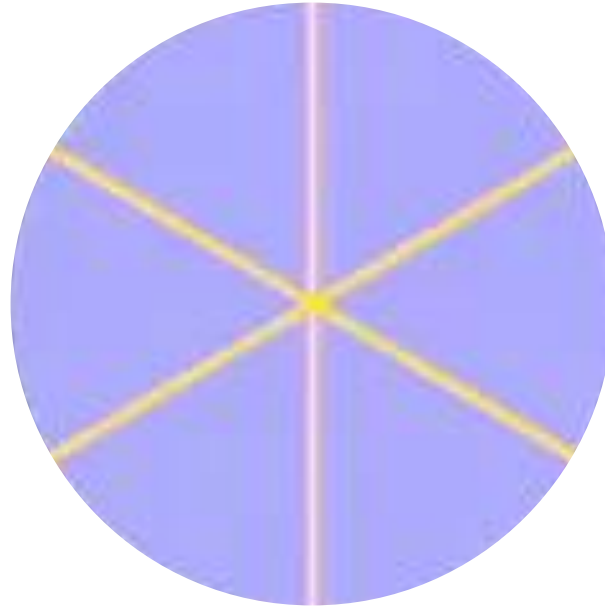
$$\delta\phi = \varphi(\varpi) e^{2\beta t}$$

ϖ = cylindrical radius



Friedman, Lindblom, Lockitch '16, following Sa '04 (stable mode),
Levin & Ushormirsky '00 (toy model)

The differential rotation winds up a background magnetic field



$$\delta B \sim B_0 \delta \phi$$

Spruit '99

Rezzola, Lamb, Shapiro '00, '01, & Markovic '01

Cuofano, Drago '10, Cuofano, Dall'Osso, Drago, Stella '12,

Chugunov '15



Stuart Shapiro, James Cook, Branson Stephens

And the growing magnetic field damps the r-mode instability when

$$\frac{dE_{linear\ mode}}{dt} = \frac{dE_{magnetic}}{dt}$$

$$\delta B \sim 10^{12} \text{ G} \propto_{-4} R_6 \Omega_3 \sqrt{\rho_{14.5}}$$

Previous studies find damping of the instability in newborn stars with an initial $B_0 > 10^{10}$ G and damping or significant alteration of the unstable mode for old accreting neutron stars.

Revisit: Two changes

1. Early studies of newborn neutron stars looked at proto-neutron stars with large magnetic fields and assumed a large saturation amplitude (amplitude at which coupling to other modes stops the growth of the r-mode)

$$\frac{1}{100} < \alpha_{\text{saturation}} < 1, \quad \text{with amplitude defined by } \delta v = \alpha \Omega$$

But a subsequent series of papers in 2nd-order perturbation theory finds

$$\alpha_{\text{saturation}} < 10^{-4}$$

(Arras, Bondarescu, Brink, Morsink, Teukolsky, Wasserman)

2. Include back-reaction of growing magnetic field on growth of differential rotation.

A 10^{12} G field is too small to change the shape or frequency of the linear r-mode.

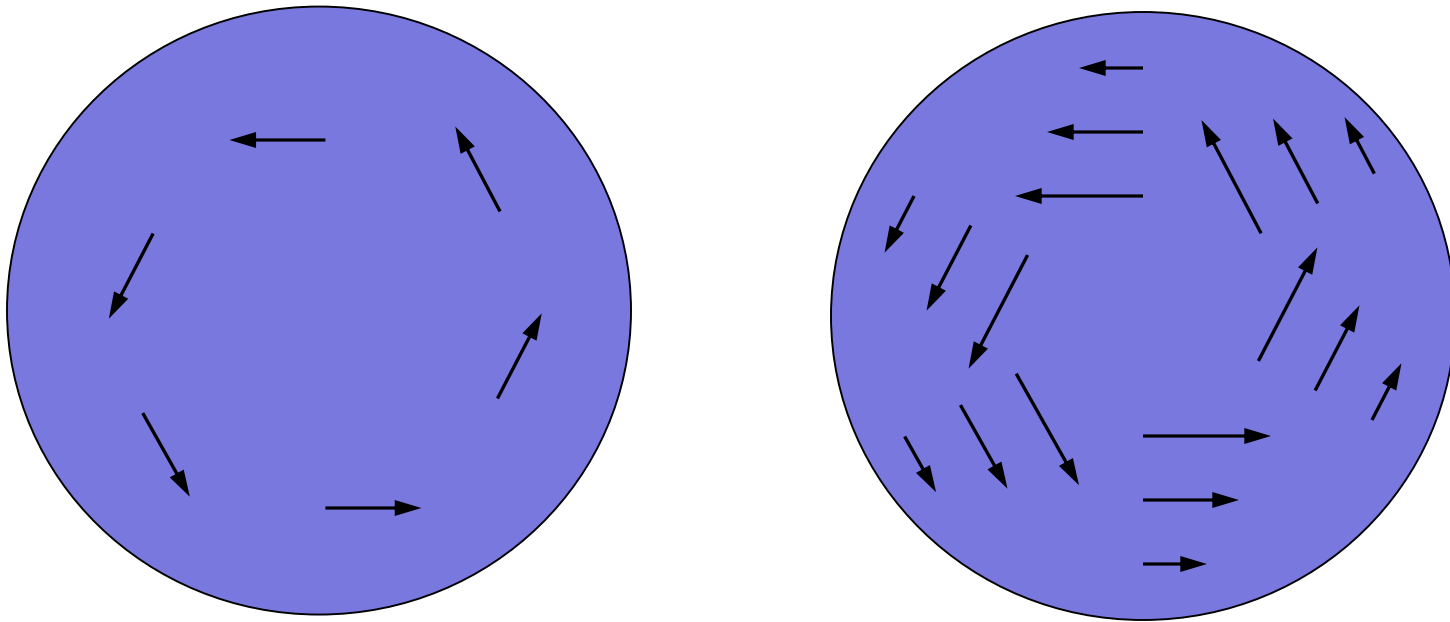
(Morsink, Rezanian, '02; Lee '05, Glampedakis, Andersson '07, S. Abbassi, M. Rieutord; Lander, Jones, Passamonti, Lander, D. I. Jones, and A. Passamonti, '10, V. Rezanian '12, Chirenti and J. Skákala '13)

But including even an initial 10^8 G has a dramatic effect on the maximum growth of differential rotation.

To see this, first look at adding differential rotation to a rotating star.

$$\Omega \rightarrow \Omega + \delta \Omega(\varpi),$$

$\varpi = \text{cylindrical radius}$



Because the perturbed star is a nearby equilibrium, the perturbation is time-independent.

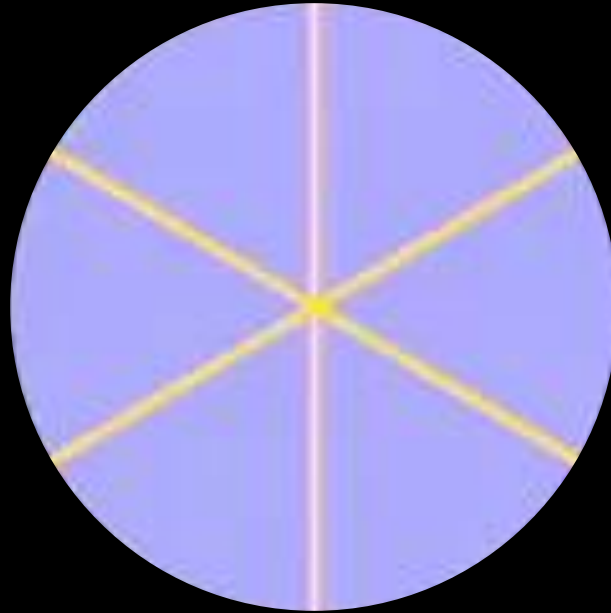
But for an equilibrium star with a magnetic field,
adding initial differential rotation is a
periodic perturbation:

Field lines wind and unwind with timescale the
Alfvén time, time for wave in magnetic field to cross

neutron star $t_A \sim 10^6 \text{ s } \sqrt{10^9 \text{ G} / B}$

$$\omega_A \sim 10^{-5} \text{ s}^{-1}$$

Here's what happens in a toy model invented by
Stuart Shapiro, the star represented by differentially
rotating fluid in a cylinder with an initially radial
magnetic field. The solution is exact.



Stuart Shapiro, James Cook, Branson Stephens

<http://research.physics.illinois.edu/cta/movies/MBRAKING/INCOMPR/evolution.html>



Stuart Shapiro, James Cook, Branson Stephens

Driven system: a dramatic difference between
a driven mode with zero-frequency and
a driven mode with nonzero frequency when
 $\omega_A > \beta$:

Before nonlinear saturation

zero-frequency

$$\partial_t \delta\Omega = \partial_t^2 \delta\phi = f_0 e^{2\beta t}$$

$$\delta\phi = \frac{f_0}{4\beta^2} e^{2\beta t}$$

frequency ω_A

$$\partial_t^2 \delta\phi + \omega_A^2 \delta\phi = f_0 e^{2\beta t}$$

$$\delta\phi \sim \frac{f_0}{\omega_A^2} e^{2\beta t} \quad \text{for } \omega_A \gg \beta$$

Angular displacement reduced to

$$\delta\phi_{\text{saturation}} \sim 10^{-1} \sqrt{\frac{B}{10^9 G}}$$

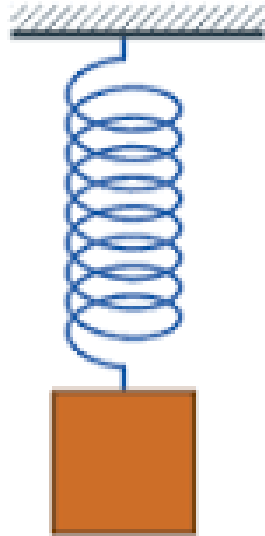
After nonlinear saturation

zero-frequency

A constant force gives
constant acceleration

frequency ω_A

$\delta\phi$ oscillates
about saturation
value



Angular displacement now limited for a normal core to

$$\delta\phi < 2 \delta\phi_{\text{saturation}}$$

This estimate may greatly overstate $\delta\phi_{max}$ because the Alfvén frequency of a type II superconductor is much higher: NS core is probably superconducting, with flux tubes carrying field $H_c \sim 10^{16}$ G

$$\omega_{A \text{ normal}} = \frac{B}{R\sqrt{4\pi\rho}} \sim 10^{-6} \text{ s}^{-1} \rightarrow$$

$$\omega_{A \text{ superconductor}} = \frac{\sqrt{BH_c}}{R\sqrt{4\pi\rho}} \sim 10^{-4} \text{ s}^{-1} \frac{B_{10}}{R_6\sqrt{\rho_{15}}}$$

$$\delta\phi_{\text{max,superconductor}} < 10^{-5} B_{10}^{-1} \alpha_{-4}^2 !$$

Conclusion

Observed magnetic fields in X-ray binaries and double neutron star systems older than 10^7 yr have $B < 10^{11}$ G.

The differential rotation possible at that field size is too small to significantly alter the linear r-mode or to drive the field to 10^{12} G.

Caveats:

Calculations done for a discrete spectrum and assuming no zero-frequency modes that wind up the magnetic field, and neglecting MRI instability.

Details:

Equation governing the 2nd order r-mode is

$$\ddot{\xi}^a + B^a_b \dot{\xi}^b + C^a_b \xi^b = f^a_{GR} + \text{terms quadratic in first - order perturbation}$$

B is anti-self adjoint, C self-adjoint
and they do not commute.

With discrete modes, nevertheless have a spectral
decomposition of the form

$$\xi^a = \sum_n \frac{\langle \hat{\xi}_n, f + Q \rangle}{2\beta - i\omega_n} \hat{\xi}_n + c.c.$$

with the mode functions $\hat{\xi}_n$ normalized by a
conserved symplectic product.

The contribution from the n th mode is again of order

$$\frac{1}{\kappa_A(4\beta^2 + \omega_A^2)}(f + Q)$$

with

$$\kappa_A = 1 - 2 \frac{\Omega}{\omega_A} \Im \frac{\int dV \rho \xi^{\varpi*} \xi^{\hat{\phi}}}{\int dV \rho |\xi|^2}.$$

MHD Euler equation

$$\partial_t \mathbf{v} + \mathbf{v} \cdot \nabla \mathbf{v} + \frac{\nabla p}{\rho} + \nabla \Phi - \frac{1}{4\pi\rho} (\nabla \times \mathbf{B}) \times \mathbf{B} = f_{GR}$$

Nonlinear perturbation:

$$\partial_t \delta \mathbf{v} + \delta \mathbf{v} \cdot \nabla \mathbf{v} + \mathbf{v} \cdot \nabla \delta \mathbf{v} + \delta \mathbf{v} \cdot \nabla \delta \mathbf{v} + \dots = \delta f_{GR}$$

The linear perturbation (r-mode) is an $m=2$ mode, proportional to $\cos(2\phi - \omega t)e^{\beta t}$

$$\begin{aligned} \partial_t \delta^{(2)} \mathbf{v} + \delta^{(2)} \mathbf{v} \cdot \nabla \mathbf{v} + \mathbf{v} \cdot \nabla \delta^{(2)} \mathbf{v} + \dots &= \delta^{(2)} f_{GR} - \delta \mathbf{v} \cdot \nabla \delta \mathbf{v} + \dots \\ &= \delta^{(2)} f_{GR} + \text{terms quadratic in first-order perturbation} \end{aligned}$$

MHD Euler equation

$$\partial_t \mathbf{v} + \mathbf{v} \cdot \nabla \mathbf{v} + \frac{\nabla p}{\rho} + \nabla \Phi - \frac{1}{4\pi\rho} (\nabla \times \mathbf{B}) \times \mathbf{B} = f_{GR}$$

Nonlinear perturbation:

$$\partial_t \delta \mathbf{v} + \delta \mathbf{v} \cdot \nabla \mathbf{v} + \mathbf{v} \cdot \nabla \delta \mathbf{v} + \delta \mathbf{v} \cdot \nabla \delta \mathbf{v} + \dots = \delta f_{GR}$$

The linear perturbation (r-mode) is an m=2 mode, proportional to

$$\cos(2\phi - \omega t) e^{\beta t}$$

The nonlinear perturbation has an **axisymmetric** part:

$$\begin{aligned}\partial_t \delta \mathbf{v} + \delta \mathbf{v} \cdot \nabla \mathbf{v} + \mathbf{v} \cdot \nabla \delta \mathbf{v} + \dots &= \delta f_{GR} - \delta \mathbf{v} \cdot \nabla \delta \mathbf{v} + \dots \\ &= \delta f_{GR} + \text{terms quadratic in the perturbation}\end{aligned}$$

and terms quadratic in the first-order perturbation are
a sum of **m=0** and **m=4** parts

$$[\cos(2\phi - \omega t) e^{\beta t}]^2 = \frac{1}{2} e^{2\beta t} + \frac{1}{2} \cos(4\phi - 2\omega t) e^{2\beta t}$$

The axisymmetric part of the nonlinear r-mode is exponentially growing differential rotation:

$$\partial_t \delta v^\phi \equiv \partial_t \delta \Omega = f e^{2\beta t}$$

$$\delta \Omega \propto e^{2\beta t}$$

