

Instability of Hairy Black Holes in shift-symmetric Horndeski theories

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RESCEU



Introduction&Motivation

Hairy BH in
shift-symmetric
scalar-tensor theory

Introduction

BH hair in scalar tensor (ST) theory

No-hair theorem holds in many ST theories

BH hair
mass, charge, angular momentum

Brans-Dicke theory

$$\mathcal{L} = \frac{R}{2} - \frac{1}{2}(\partial\phi)^2 - U(\phi) \quad (\text{in Einstein frame})$$

Hawking (1972); Bekenstein (1996).....

Covariant Galileon

$$\mathcal{L} \supset (\partial\phi)^2 \square\phi, \dots \quad (\text{spherically symmetric BHs})$$

Hui, Nicolis (2013)

and more...

However...

One consider shift-symmetric ST theory **with time-dependent scalar field**

→ BH solutions are found with non-trivial **scalar hair**

Bavichev, Charmousis(2014)

Dressing BH in shift-symmetric ST theory

Shift & reflection symmetry: $\phi \rightarrow \phi + \text{const.}$, $\phi \rightarrow -\phi$

$$\mathcal{L} = [\zeta R - \eta(\partial\phi)^2 + \beta G^{\mu\nu}\partial_\mu\phi\partial_\nu\phi - 2\Lambda] \quad \zeta > 0, \eta, \beta : \text{const}$$

Shift symmetry

$$\phi \rightarrow \phi + \text{const.} \longrightarrow$$

EOM for scalar

$$\nabla_\mu J^\mu = 0$$

$$J^\mu = (\eta g^{\mu\nu} - \beta G^{\mu\nu})\partial_\nu\phi$$

Λ : cosmological constant

Assumptions in Bavichev and Charmousis paper

$$ds^2 = -A(r)dt^2 + \frac{1}{B(r)}dr^2 + r^2d\Omega^2 \quad \text{static and spherical symmetric}$$

$$J^r = 0 \longrightarrow \text{Current } J^2 = J_\mu J^\mu \text{ regular at the horizon}$$

$$\phi(t, r) = qt + \psi(r) \longrightarrow \text{Space-time is static in shift-symmetric theory}$$

Dressing BH in shift-symmetric ST theory

Shift & reflection symmetry: $\phi \rightarrow \phi + \text{const.}$, $\phi \rightarrow -\phi$

$$\mathcal{L} = [\zeta R - \eta(\partial\phi)^2 + \beta G^{\mu\nu}\partial_\mu\phi\partial_\nu\phi - 2\Lambda] \quad \zeta > 0, \eta, \beta : \text{const}$$

does not contain bare ϕ

contains derivative term $\partial_\mu\phi$

→ Time dependence term dose not appear in the theory.

(* We are not afraid that value of scalar field is unbound.)

$$ds^2 = -A(r)dt^2 + \frac{1}{B(r)}dr^2 + r^2d\Omega^2 \quad \text{static and spherical symmetric}$$

$J^r = 0 \rightarrow$ Current $J^2 = J_\mu J^\mu$ regular at the horizon

$\phi(t, r) = qt + \psi(r) \rightarrow$ **Space-time is static in shift-symmetric theory**

Dressing BH in shift-symmetric ST theory

$$\mathcal{L} = [\zeta R - \eta(\partial\phi)^2 + \beta G^{\mu\nu}\partial_\mu\phi\partial_\nu\phi - 2\Lambda] \quad \phi(t, r) = qt + \psi(r)$$

Stealth Schwarzschild

$$A(r) = B(r) = 1 - \frac{\mu}{r} \quad \mu : \text{const.}$$

$$\phi_{\pm} = qt \pm q\mu \left[2\sqrt{\frac{r}{\mu}} + \log \frac{\sqrt{r} - \sqrt{\mu}}{\sqrt{r} + \sqrt{\mu}} \right] + \phi_0$$

Self-tuned Schwarzschild-de-sitter

$$A(r) = B(r) = 1 - \frac{\mu}{r} + \frac{\eta}{3\beta}r^2 \rightarrow \Lambda_{\text{eff}} = -\frac{\zeta\eta}{\beta} \neq \Lambda$$

This metric represent Schwarzschild BH in the presence of cosmological constant.

We do not conceive huge bare Λ through the metric.

Hairy BH solutions in the generalized theory

$$\mathcal{L} = [\zeta R - \eta(\partial\phi)^2 + \beta G^{\mu\nu}\partial_\mu\phi\partial_\nu\phi - 2\Lambda] \quad \phi(t, r) = qt + \psi(r)$$

Stealth Schwarzschild

$$A(r) = B(r) = 1 - \frac{\mu}{r} \quad \mu : \text{const.}$$

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Self-tuned Schwarzschild-de-sitter

$$A(r) = B(r) = 1 - \frac{\mu}{r} + \frac{\eta}{3\beta}r^2 \quad \rightarrow \quad \Lambda_{\text{eff}} = -\frac{\zeta\eta}{\beta} \neq \Lambda$$

Babichev, Charmousis(2014) can be generalized

$$\mathcal{L} = G_2(X) + G_4(X)R + G_{4X} [(\square\phi)^2 - (\nabla_\mu\nabla_\nu\phi)^2]$$

$$G_{4X} := \frac{\partial G_4}{\partial X} \quad X := -\frac{1}{2}(\partial\phi)^2 \quad \text{Kobayashi, Tanahashi(2014)}$$

The most general 2nd-order theory with shift & reflection symmetries

Hairy BH solutions in the generalized theory

$$\mathcal{L} = [\zeta R - \eta(\partial\phi)^2 + \beta G^{\mu\nu}\partial_\mu\phi\partial_\nu\phi - 2\Lambda] \quad \phi(t, r) = qt + \psi(r)$$

Stealth Schwarzschild

$$A(r) = B(r) = 1 - \frac{\mu}{r} \quad \mu : \text{const.}$$

$$\phi_{\pm} = qt \pm q\mu \left[2\sqrt{\frac{r}{\mu}} + \log \frac{\sqrt{r} - \sqrt{\mu}}{\sqrt{r} + \sqrt{\mu}} \right] + \phi_0$$

Many of found BHs are

X constant solutions

Self-tuned Schwarzschild-de-sitter

$$A(r) = B(r) = 1 - \frac{\mu}{r} + \frac{\eta}{3\beta}r^2 \rightarrow \Lambda_{\text{eff}} = -\frac{\zeta\eta}{\beta} \neq \Lambda$$

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$$\mathcal{L} = G_2(X) + G_4(X)R + G_{4X} [(\square\phi)^2 - (\nabla_\mu\nabla_\nu\phi)^2]$$

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The most general 2nd-order theory with shift & reflection symmetries

Motivation

Stealth Schwarzschild sol and
Self-tuned Schwarzschild-de-sitter sol
are very interesting solutions.

How about stability of BHs?

Instability of Hairy BH in shift symmetric Horndeski theories

HO, T. Kobayashi, T. Suyama

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BH perturbations with time-dependent scalar

$$\mathcal{L} = G_2(X) + G_4(X)R + G_{4X} \left[(\square\phi)^2 - (\nabla_\mu \nabla_\nu \phi)^2 \right] \quad ds^2 = -A(r)dt^2 + \frac{1}{B(r)}dr^2 + r^2d\Omega^2$$

$$\phi(t, r) = qt + \psi(r)$$

Basic Procedure

action 2nd-order in perturbations

Hamiltonian analysis

stability conditions

Set up

The most general 2nd-order theory with shift & reflection symmetries

$$\mathcal{L} = G_2(X) + G_4(X)R + G_{4X} \left[(\square\phi)^2 - (\nabla_\mu \nabla_\nu \phi)^2 \right]$$

$$\phi(t, r) = qt + \psi(r), \quad G_{4X} := \frac{\partial G_4}{\partial X}$$

Perturbations can be written as following eqs (odd-parity)

$$g_{\mu\nu} = g_{\mu\nu}^{(0)} + h_{\mu\nu}$$

$$ds^2 = -A(r)dt^2 + \frac{1}{B(r)}dr^2 + r^2d\Omega^2$$

$$h_{tt} = 0, \quad h_{tr} = 0, \quad h_{rr} = 0$$

$$E_{ab} = \sqrt{\det\gamma}\epsilon_{ab}$$

$$h_{ta} = \sum_{l,m} h_{0,lm}(t, r) E_{ab} \partial^b Y_{lm}(\theta, \varphi)$$

γ_{ab} two-dim metric on the sphere

ϵ_{ab} Levi-Civita symbol

$$h_{ra} = \sum_{l,m} h_{1,lm}(t, r) E_{ab} \partial^b Y_{lm}(\theta, \varphi)$$

$$h_{ab} = \sum_{l,m} \cancel{h_{2,lm}}(t, r) [E_a{}^c \nabla_c \nabla_b Y_{lm}(\theta, \varphi) + E_b{}^c \nabla_c \nabla_a Y_{lm}(\theta, \varphi)]$$

gauge fixed (Regge-Wheeler gauge)

BH perturbations with time-dependent scalar

$$\mathcal{L} = G_2(X) + G_4(X)R + G_{4X} \left[(\square\phi)^2 - (\nabla_\mu \nabla_\nu \phi)^2 \right] \quad ds^2 = -A(r)dt^2 + \frac{1}{B(r)}dr^2 + r^2d\Omega^2$$
$$\phi(t, r) = qt + \psi(r), \quad X := -\frac{1}{2}(\partial\phi)^2$$

action 2nd-order in perturbations

Quadratic Lagrangian

$$\frac{2l+1}{2\pi} \mathcal{L}^{(2)} = A_1 h_0^2 + A_2 h_1^2 + A_4 h_0 h_1 + A_3 \left(\dot{h}_1^2 - 2h'_0 \dot{h}_1 + h'^2_0 + \frac{4}{r} h_0 \dot{h}_1 \right)$$
$$\dot{h}_i := \frac{\partial h_i}{\partial t}, \quad h'_i := \frac{\partial h_i}{\partial r}$$

$$A_1 = -\frac{l(l+1)(r^2 A^2 B A' G_4 - 2q^2 r^2 A B A' G_{4X} + \dots)}{A^{5/2} B^{1/2}}$$

$$A_1, A_2, A_3, A_4 \supset A(r), B(r), G_2, G_4, \dots$$

BH perturbations with time-dependent scalar

$$\mathcal{L} = G_2(X) + G_4(X)R + G_{4X} \left[(\square\phi)^2 - (\nabla_\mu \nabla_\nu \phi)^2 \right], \quad ds^2 = -A(r)dt^2 + \frac{1}{B(r)}dr^2 + r^2d\Omega^2$$
$$\phi(t, r) = qt + \psi(r), \quad X := -\frac{1}{2}(\partial\phi)^2$$

If we solve the perturbations...

$$\begin{aligned} \frac{2l+1}{2\pi} \mathcal{L}^{(2)} = & A_1 h_0^2 + A_2 h_1^2 + A_4 h_0 h_1 \\ & + A_3 \left(\dot{h}_1^2 - 2h'_0 \dot{h}_1 + h'^2_0 + \frac{4}{r} h_0 \dot{h}_1 \right) \end{aligned}$$

 variation with respect to h_0

$$[A_3(h'_0 - \dot{h}_1)]' = A_1 h_0 + A_4 h_1 + \frac{4}{r} A_3 \dot{h}_1$$

constraint equation, non dynamical h_0

we cannot solve straightforwardly the constraint

BH perturbations with time-dependent scalar

$$\mathcal{L} = G_2(X) + G_4(X)R + G_{4X} \left[(\square\phi)^2 - (\nabla_\mu \nabla_\nu \phi)^2 \right] \quad ds^2 = -A(r)dt^2 + \frac{1}{B(r)}dr^2 + r^2 d\Omega^2$$
$$\phi(t, r) = qt + \psi(r), \quad X := -\frac{1}{2}(\partial\phi)^2$$

field redefinition

$$\begin{aligned} \frac{2l+1}{2\pi} \mathcal{L}^{(2)} &= A_1 h_0^2 + A_2 h_1^2 + A_4 h_0 h_1 \\ &\quad + A_3 \left(\dot{h}_1^2 - 2h'_0 \dot{h}_1 + h'^2_0 + \frac{4}{r} h_0 \dot{h}_1 \right) \end{aligned}$$

 **To remove non-dynamical h_0 we introduce a new field χ**

$$\begin{aligned} \frac{2l+1}{2\pi} \mathcal{L}^{(2)} &= \left(A_1 - \frac{2(rA_3)'}{r^2} \right) h_0^2 + A_2 h_1^2 \\ &\quad + A_3 \left[-\chi^2 + 2\chi \left(\dot{h}_1 - h'_0 + \frac{2}{r} h_0 \right) \right] + A_4 h_0 h_1 \end{aligned}$$

BH perturbations with time-dependent scalar

$$\mathcal{L} = G_2(X) + G_4(X)R + G_{4X} \left[(\square\phi)^2 - (\nabla_\mu \nabla_\nu \phi)^2 \right] \quad ds^2 = -A(r)dt^2 + \frac{1}{B(r)}dr^2 + r^2d\Omega^2$$

$$\phi(t, r) = qt + \psi(r), \quad X := -\frac{1}{2}(\partial\phi)^2$$

field redefinition

$$\begin{aligned} \frac{2l+1}{2\pi} \mathcal{L}^{(2)} &= \left(A_1 - \frac{2(rA_3)'}{r^2} \right) h_0^2 + A_2 h_1^2 \\ &\quad + A_3 \left[-\chi^2 + 2\chi \left(\dot{h}_1 - h_0' + \frac{2}{r}h_0 \right) \right] + A_4 h_0 h_1 \end{aligned}$$

↓

$$\begin{aligned} h_0 &= -\frac{2r \{ 2a_2 [r(\chi a_3)' + 2\chi a_3] + r\dot{\chi} a_3 a_4 \}}{4a_2[r^2 a_1 - 2(ra_3)'] - r^2 a_4^2}, \\ h_1 &= \frac{4a_3 \dot{\chi} [r^2 a_1 - 2(ra_3)'] + 2ra_4 [r(\chi a_3)' + 2a_3 \chi]}{4a_2[r^2 a_1 - 2(ra_3)'] - r^2 a_4^2}. \end{aligned}$$

$$\frac{2l+1}{2\pi} \mathcal{L}^{(2)} = \frac{l(l+1)}{(l-1)(l+2)} \sqrt{\frac{B}{A}} (b_1 \dot{\chi}^2 - b_2 \chi'^2 + b_3 \dot{\chi} \chi' - l(l+1)b_4 \chi^2 - V(r)\chi^2)$$

BH perturbations with time-dependent scalar

$$\mathcal{L} = G_2(X) + G_4(X)R + G_{4X} \left[(\square\phi)^2 - (\nabla_\mu \nabla_\nu \phi)^2 \right], \quad ds^2 = -A(r)dt^2 + \frac{1}{B(r)}dr^2 + r^2d\Omega^2$$
$$\phi(t, r) = qt + \psi(r), \quad X := -\frac{1}{2}(\partial\phi)^2$$

Hamiltonian analysis

$$\frac{2l+1}{2\pi} \mathcal{L}^{(2)} = \frac{l(l+1)}{(l-1)(l+2)} \sqrt{\frac{B}{A}} (b_1 \dot{\chi}^2 - b_2 \chi'^2 + b_3 \dot{\chi}\chi' - l(l+1)b_4 \chi^2 - V(r)\chi^2)$$



$$\pi = \frac{\partial \tilde{\mathcal{L}}}{\partial \dot{\chi}}$$

$$H = \frac{1}{2} \int dr \sqrt{\frac{B}{A}} \left\{ \frac{1}{b_1} \left(\sqrt{\frac{A}{B}}\pi - \frac{1}{2}b_3\chi' \right)^2 + b_2\chi'^2 + [l(l+1)b_4 + V]\chi^2 \right\}$$

Hamiltonian must be positive definite...

$$b_1 > 0, \quad b_2 > 0, \quad b_4 > 0$$

BH perturbations with time-dependent scalar

$$\mathcal{L} = G_2(X) + G_4(X)R + G_{4X} \left[(\square\phi)^2 - (\nabla_\mu \nabla_\nu \phi)^2 \right], \quad ds^2 = -A(r)dt^2 + \frac{1}{B(r)}dr^2 + r^2d\Omega^2$$
$$\phi(t, r) = qt + \psi(r), \quad X := -\frac{1}{2}(\partial\phi)^2$$

Stability conditions

$$b_1 > 0, \quad b_2 > 0, \quad b_4 > 0$$

$$\mathcal{F} = 2 \left[G_4 - \frac{q^2}{A} G_{4X} \right] > 0,$$

$$\mathcal{G} = 2 \left[G_4 - 2XG_{4X} + \frac{q^2}{A} G_{4X} \right] > 0,$$

$$\mathcal{H} = 2(G_4 - 2XG_{4X}) > 0$$



Application to sample solution

ST theory: $\mathcal{L} = G_2(X) + G_4(X)R + G_{4X} [(\square\phi)^2 - (\nabla_\mu\nabla_\nu\phi)^2]$

$$\phi(t, r) = qt + \psi(r), X := -\frac{1}{2}(\partial\phi)^2, G_{4X} := \frac{\partial G_4}{\partial X}, ds^2 = -A(r)dt^2 + \frac{1}{B(r)}dr^2 + r^2d\Omega^2$$

Stealth sol, self-tuned de-sitter sol: $X = \text{const.}$

$$\mathcal{F} = 2 \left[G_4 \underset{\text{const}}{\boxed{}} - \frac{q^2}{A} G_{4X} \underset{\text{const}}{\boxed{}} \right] > 0,$$

$$\mathcal{G} = 2 \left[G_4 \underset{\text{const}}{\boxed{}} - 2XG_{4X} \underset{\text{const}}{\boxed{}} + \frac{q^2}{A} G_{4X} \underset{\text{const}}{\boxed{}} \right] > 0,$$

$$\mathcal{H} = 2 \left(G_4 \underset{\text{const}}{\boxed{}} - 2XG_{4X} \underset{\text{const}}{\boxed{}} \right) > 0$$

Application to sample solution

ST theory: $\mathcal{L} = G_2(X) + G_4(X)R + G_{4X} [(\square\phi)^2 - (\nabla_\mu\nabla_\nu\phi)^2]$

$$\phi(t, r) = qt + \psi(r), X := -\frac{1}{2}(\partial\phi)^2, G_{4X} := \frac{\partial G_4}{\partial X}, ds^2 = -A(r)dt^2 + \frac{1}{B(r)}dr^2 + r^2d\Omega^2$$

Stealth sol, self-tuned de-sitter sol: $X = \text{const.}$

$$\mathcal{F} = 2 \left[G_4 - \frac{q^2}{A} G_{4X} \right] > 0,$$

these terms are of
opposite sign

$$\mathcal{G} = 2 \left[G_4 - 2XG_{4X} + \frac{q^2}{A} G_{4X} \right] > 0,$$

$$\mathcal{H} = 2(G_4 - 2XG_{4X}) > 0$$



near the horizon

$$\mathcal{F}\mathcal{G} \simeq -4 \left(\frac{q^2}{A} G_{4X} \right)^2 < 0$$

X=const solutions are unstable

Summary

Hairy BH solutions in shift-symmetric ST theory

Very interesting solutions are found

BH stability conditions

We obtain stability conditions (Hamiltonian analysis)

$$\mathcal{F} > 0, \mathcal{G} > 0, \mathcal{H} > 0$$

Hairy BH are unstable due to time-dependent scalar

$$X := -\frac{1}{2}(\partial\phi)^2 = \text{const.}$$

BH solutions are unstable

Back up slides

No-hair theorem

BH hair in scalar tensor (ST) theory

Brans-Dicke theory

$$\mathcal{L} = \frac{R}{2} - \frac{1}{2}(\partial\phi)^2 - U(\phi)$$

Hawking (1972); Bekenstein (1996).....

static, Einstein flame

standard scalar-tensor theory hold no-hair theorem

Conformally coupled scalar field

$$\mathcal{L} = \frac{R}{2} - \frac{1}{2}(\partial\phi)^2 - \frac{1}{12}R\phi^2$$

BBMB solution

Bocharova, et.al (1970)

static, spherical symmetric,
scalar is **unbound**

Hairy BH solutions

$$\mathcal{L} = [\zeta R - \eta(\partial\phi)^2 + \beta G^{\mu\nu}\partial_\mu\phi\partial_\nu\phi - 2\Lambda] \quad \phi(t, r) = qt + \psi(r)$$

Stealth Schwarzschild

$$A(r) = B(r) = 1 - \frac{\mu}{r} \quad \mu : \text{const.}$$

$$\phi_{\pm} = qt \pm q\mu \left[2\sqrt{\frac{r}{\mu}} + \log \frac{\sqrt{r} - \sqrt{\mu}}{\sqrt{r} + \sqrt{\mu}} \right] + \phi_0$$

Metric is Schwarzschild metric, but scalar field is non-trivial and regular at the horizon.

Consider Eddington-Finkelstein coordinates

$$v = t + \int (fh)^{-1/2} dr$$

→ $\phi_+ = q \left[v - r + 2\sqrt{\mu r} - 2\mu \log \left(\sqrt{\frac{r}{\mu}} + 1 \right) \right] + \text{const}$

No-hair theorem

Covariant Galileon

$$\mathcal{L} \supset (\partial\phi)^2 \square\phi, \dots$$

Hui, Nicolis (2013)

static, spherically symmetric, asymptotically flat

There are two types of loopholes

Gauss-Bonnet combination

Sotiriou, Zhou (2014)

linearly time dependence

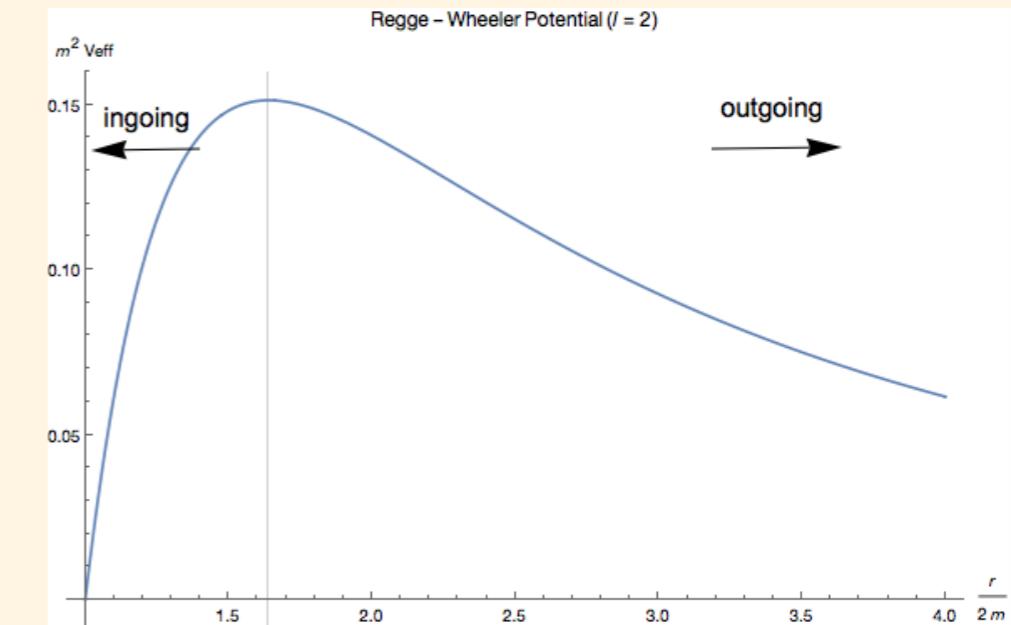
Bavichev, Charmousis(2014)

Regge-Wheeler-Zerilli eq

Regge-Wheeler-Zerilli eqs

$$\frac{\partial^2 F(t, r)}{\partial t^2} - \frac{\partial^2 F(t, r)}{\partial r_*^2} + V(r)F(t, r) = 0$$

F satisfied the boundary right conditions



→ $\frac{\partial}{\partial t} \int_{-\infty}^{\infty} dr_* \left[\left| \frac{\partial F}{\partial t} \right|^2 + V |F|^2 + \left| \frac{\partial F}{\partial r} \right|^2 \right] = -2(|\dot{f}|^2 + |\dot{g}|^2) < 0$

F is decaying function or growing function

→ BH is stable or unstable

We focus on short length mode perturbations
Our stability conditions is necessary condition...
but classically and quantum mechanically unstable

BH perturbations with time-dependent scalar

$$\phi(t, r) = qt + \psi(r), \quad ds^2 = -A(r)dt^2 + \frac{1}{B(r)}dr^2 + r^2d\Omega^2$$

Hamiltonian

$$\frac{2l+1}{2\pi} \mathcal{L}^{(2)} = \frac{l(l+1)}{(l-1)(l+2)} \sqrt{\frac{B}{A}} (b_1 \dot{\chi}^2 - b_2 \chi'^2 + b_3 \dot{\chi} \chi' - l(l+1)b_4 \chi^2 - V(r)\chi^2)$$

we suppress l-factor

$$\tilde{\mathcal{L}} = \frac{1}{2} \sqrt{\frac{B}{A}} \left\{ b_1 \dot{\chi}^2 - b_2 \chi'^2 + b_3 \dot{\chi} \chi' - [l(l+1)b_4 + V] \chi^2 \right\}.$$

$$H = \frac{1}{2} \int dr \sqrt{\frac{B}{A}} \left\{ \frac{1}{b_1} \left(\sqrt{\frac{A}{B}} \pi - \frac{1}{2} b_3 \chi' \right)^2 + b_2 \chi'^2 + [l(l+1)b_4 + V] \chi^2 \right\}$$

kinetic and radial instability $b_1 > 0, \quad b_2 > 0.$

To avoid

large l instability $b_4 > 0$

$l = 1$ mode: we rethink about gauge conditions

$$\frac{2l+1}{2\pi} \mathcal{L}^{(2)} = \frac{l(l+1)}{(l-1)(l+2)} \sqrt{\frac{B}{A}} (b_1 \dot{\chi}^2 - b_2 \chi'^2 + b_3 \dot{\chi}\chi' - l(l+1)b_4 \chi^2 - V(r)\chi^2)$$

$$l = 1$$

$$h_{tt} = 0, \quad h_{tr} = 0, \quad h_{rr} = 0$$

$$h_{ta} = \sum_{l,m} h_{0,lm}(t,r) E_{ab} \partial^b Y_{lm}(\theta, \varphi)$$

$$h_{ra} = \sum_{l,m} h_{1,lm}(t,r) E_{ab} \partial^b Y_{lm}(\theta, \varphi)$$

$$h_{ab} = \sum_{l,m} h_{2,lm}(t,r) [E_a{}^c \nabla_c \nabla_b Y_{lm}(\theta, \varphi) + E_b{}^c \nabla_c \nabla_a Y_{lm}(\theta, \varphi)]$$

automatically drop

Coefficients

$$\mathcal{L} = G_2(X) + G_4(X)R + G_{4X}\left[(\square\phi)^2 - (\nabla_\mu\nabla_\nu\phi)^2\right] \quad ds^2 = -A(r)dt^2 + \frac{1}{B(r)}dr^2 + r^2d\Omega^2$$

$$X := -\frac{1}{2}(\partial\phi)^2$$

$$\frac{2l+1}{2\pi}\mathcal{L}^{(2)}=A_1h_0^2+A_2h_1^2+A_4h_0h_1$$

$$+A_3\left(\dot{h}_1^2-2h_0'\dot{h}_1+h_0'^2+\frac{4}{r}h_0\dot{h}_1\right)$$

$$A_1=\frac{l(l+1)}{r^2}\left[\frac{d}{dr}\left(r\sqrt{\frac{B}{A}}\mathcal{H}\right)+\frac{(l-1)(l+2)}{2\sqrt{AB}}\mathcal{F}\right],$$

$$A_2=-\frac{(l-1)l(l+1)(l+2)}{2}\frac{\sqrt{AB}}{r^2}\mathcal{G},$$

$$A_3=\frac{l(l+1)}{2}\sqrt{\frac{B}{A}}\mathcal{H},$$

$$A_4=\frac{(l-1)l(l+1)(l+2)}{r^2}\sqrt{\frac{B}{A}}\mathcal{J}$$

$$\mathcal{F}=2\left(G_4-\frac{q^2}{A}G_{4X}\right),$$

$$\mathcal{G}=2\left(G_4-2XG_{4X}+\frac{q^2}{A}G_{4X}\right),$$

$$\mathcal{H}=2\left(G_4-2XG_{4X}\right),$$

$$\mathcal{J}=2qG_{4X}\psi'$$